

# MASSIMILIANO PATACCHIOLA

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Name Massimiliano  
Surname Patacchiola  
Address Plymouth, Devon, United Kingdom  
Blog <http://mpatacchiola.github.io/blog>  
GitHub <https://github.com/mpatacchiola>  
Nationality Italian  
Sex Male

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## Profile

Researcher specialised in computational modelling through machine learning and deep learning techniques. Interdisciplinary skills in robotics, artificial intelligence, neuroscience and experimental psychology. Interests: trust and transparency in AI, deep learning, reinforcement learning, robotics.

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## Education

- 2015-present PhD candidate in “Cognitive Robotics and Computational Modelling”. Plymouth University, School of Computing, Electronics and Mathematics. United Kingdom. Supervisors: Angelo Cangelosi, Torbjorn Dahl, Giorgio Metta  
[www.thrive-project.org](http://www.thrive-project.org)
- 2009-2011 MSc in “Cognitive Neuroscience”. La Sapienza University. Rome, Italy. Supervisors: Stefano Puglisi Allegra, Gianluca Baldassarre, Domenico Parisi
- 2006-2009 BSc in “Experimental Cognitive Psychology”. La Sapienza University. Rome, Italy. Supervisor: Marta Olivetti Belardinelli
- 1999-2004 Secondary School. Scientific Course: National Plan of Computer Science. Rieti, Italy. It gives entry to university. Main subjects: computer science, mathematics (linear algebra, pre-calculus, calculus), physics, biology, English, French.
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## Work/Research Experience

- 2015-present Teaching assistant and demonstrator. Plymouth University. United Kingdom. I prepared and presented the material for individual lessons and workshops on Deep Learning, Bayesian Networks and Robotics.
- 2012-2015 Robotics Engineer. Eurolink Systems group. Rome. Italy. My duties involved creating algorithms and models for the control of UGV (Unmanned Ground Vehicle) and UAV (Unmanned Aerial Vehicle) ([www.eurolinksystems.com](http://www.eurolinksystems.com))
- 2011-2012 Internship, LARAL (Laboratory of Artificial Life and Robotics). Institute of Cognitive Sciences and Technologies. Rome, Italy. My duties involved creating cognitive models for simulations in Evolutionary Robotics (<http://laral.istc.cnr.it>)

2008-2009 Placement, ECONA (Research Centre for Cognitive Elaboration on Natural and Artificial Systems). La Sapienza University. Rome, Italy. Research project on visual perception and memory (<https://web.uniroma1.it/econa>)

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## Technical Skills

**Machine Learning** -Programming experience with TensorFlow for Deep Learning applications [[GitHub](#)]  
-Experience with Artificial Neural Networks and the most recent Deep Learning techniques (e.g MLP, CNN, ResNet, GAN, Inception, etc).  
-Experience with supervised, unsupervised learning algorithms, reinforcement learning (DQN, Double DQN, MC, SARSA, etc), and Bayesian networks.

**Robotics** -I developed libraries for the control of humanoid robots, drones and autonomous ground rover.  
-Experience with the most important software tools for Robotics and Computer Vision (e.g. ROS, YARP, NAOqi, OpenAI Gym, OpenCV).

**Computer Science** -Advanced knowledge of Unix OS (Shell, Bash scripting, SSH).  
-Proficiency in Python (Numpy) and familiarity with several programming languages (C/C++, C#, Java, Visual Basic, HTML, PHP, JavaScript).

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## Languages

Italian (native speaker), English (advanced), French (intermediate)

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## Awards, Fellowships and Scholarships

2018-present Associate Fellowship, Higher Education Academy (HEA). Programme that supports early career researchers who have responsibility for teaching and learning.

03-2016 Academic Hardware Grant, NVIDIA corporation. I received a Tesla K40 GPU in support of a project on head pose estimation through convolutional neural networks.

2012-present Member, Mensa International. Society for people with high intelligence quotient.

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## Talks, Conferences, Workshops, Media

27-07-2017 (Extra) BBC documentary. Hyper Evolution: Rise of the Robots. Episode 1 and 2, the iCub humanoid robot at CRNS lab.

2015-present (Reviewer) I have been the reviewer for different conferences and journals: ICRA (International Conference on Robotics and Automation), IROS (International Conference on Intelligent Robots and Systems), IEEE Transactions on Cognitive and Developmental Systems.

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## Selected Publications [\[scholar\]](#)

Polvara\* R., **Patacchiola\* M.**, Sharma, S., Wan J., Manning, A., Sutton R., Cangelosi, A. (under review). “Autonomous Quadrotor Landing using Deep Reinforcement Learning”. \*Co-first authors, [\[arxiv\]](#)

**Patacchiola, M.**, Cangelosi, A. (2017). “Head Pose Estimation in the Wild using Convolutional Neural Networks and Adaptive Gradient Methods”. *Pattern Recognition*, vol. 71, pp. 132-143. [\[pdf\]](#) [\[GitHub\]](#)

Zanatto, D., **Patacchiola, M.**, Goslin, J., Cangelosi, A. (2016). “Priming antropomorphism: Can the credibility of humanlike robots be transferred to non-humanlike robots?”. *In Proceeding of the Eleventh Annual ACM/IEEE International Conference on Human Robot Interaction*, Christchurch, New Zeland, pp. 534-544. [\[pdf\]](#)

Paglieri, F., Parisi D., **Patacchiola, M.**, Petrosino, G. (2015). “Investigating intertemporal choice trough experimental evolutionary robotics”. *Behavioural Processes*, vol. 115, pp. 1-18. [\[pdf\]](#)